Planetary Sciences # 4

57A- Class 15

A way by which we can gain knowledge about the internal composition of planets is by the inertia moment, which depends on the internal mass distribotion of the planet, and is measurable. Consider the geometry Lelow, where R is the cylindrical to the axis of rotation. the inertia moment is R the inertia moment is $\mathcal{I} = \int \rho(\mathbf{r}) R^2 dV$ $dV = r^2 \sin \theta \, d\theta \, d\phi \, dr$ $R = r \sin \theta$ For constant density, the inertia moment is I=27p (rsinododr $I = p \int R^2 dN$ $= 2\pi \ln \frac{r}{5} \int \sin^3 \theta d\theta$ $= 2 \pi p \cdot r \left[\cdot \frac{4}{5} = \frac{8 \pi}{15} \cdot p R^{5} \right]$ $P = \frac{M}{4\Pi \cdot R^{3}} \rightarrow I = \frac{RT}{5} \cdot \frac{M}{5} \cdot \frac{3}{5} \times \frac{2}{5} \times \frac{2}{5$

Devictions from constant density will lead to devictions from the 2/5 MR² value. Let us consider a 2-phase Coret envelope model:



We can conclude that I is related to oblateness and density difference between core and unvelope.

More fundamentally $\frac{1}{MR^{2}} = \frac{2}{3} \left(1 - \frac{2}{5} \sqrt{\frac{5q}{2s} - 1} \right)$ Where qr is the ratio between centrifugal force and gravity, and E is the oblateness $q_r = \frac{\omega_{rot}^2 R^3}{GM}$ $\mathcal{E} = \mathcal{R}_{\mathcal{C}} - \mathcal{R}_{\mathcal{P}}$ Rp Another way to measure qr is from the gravitatio-nal moments. The deviation from sphericity (an be written as $\overline{\mathcal{F}}_{\mathcal{F}}\left[r,\partial,\phi\right] = -\left(\underbrace{\mathcal{GM}}_{r} + \Delta \overline{\mathcal{F}}_{\mathcal{F}}\left(r,\partial,\phi\right)\right)$ with $\Delta \overline{d}_{g}(r, \phi_{1} \theta) = \underline{CH} \underbrace{\sum}_{r} \underbrace{\sum}_{h=0}^{\infty} \left(\frac{R}{r} \right)^{h} \left[(h_{h} \cos(m\phi) + S_{mn} \sin(m\phi)) \right] \Gamma_{hm}(\cos \theta)$ being an expansion in spherical harmonics. We can simplify this expression by assuming azimuthal symmetry

Then Shm=D and for m = O all Cun arezero. The only non-zero coefficient is Sho $\Delta \overline{\overline{g}}(r, \theta) = \underline{GM} \sum_{n=1}^{\infty} \left(\frac{R}{n}\right)^{n} C_{n0} T_{n0} (\cos \theta)$ we can now define Jn = - Cno and have $\frac{\Phi_{g}(r_{I}\theta_{I}\phi) = -\frac{GM}{r} \left[1 - \frac{\varepsilon}{h} \sum_{n=1}^{\infty} P_{n}(\cos\theta) \left(\frac{R}{r}\right)^{h} \right]$ where The (2050) are the Legendre polynomials. The first few are Pr(2) h 0 $\frac{\pi}{\frac{1}{2}(3\pi^{2}+1)}$ $\frac{1}{2}(5\pi^{3}-3\pi)$ $\frac{1}{8}(35\pi^{4}-30\pi^{2}+3)$ 3 4 In the slides one sees the shapes of the J_2 , Jy and J effects. The Jz is related to pure oblateness, given by $J_2 \simeq \frac{9}{2}$.

Measuring I, we can plot the values (see slides) to reveal a trend: the noon is quite dose to homogeneous, and there is a downward trend to less homogeneity towards higher masses, indicating wass is setting concentrated hear the center : planets have denser cores and lighter envelopes.

Jupiter is an outlier in the trend, which is odd since it is of so high mass Indeed, the data is inconclusive over whether upiter has a core or not. This opens the possibility that may be Jupiter did NoT form by are accretion, but by a top-down mechanism similar to star Formation: direct gravitational instability from the gas disk.

Gravitational (disk) instability

let us consider the equations of hydrodynamics St + (r. D) b = - b D. r $\frac{\partial u}{\partial t} + (V \cdot \nabla) V = -\frac{1}{l} \nabla_{f} - \nabla_{f}$

And add to it the Poisson equation for self-gravity $\nabla_{\phi}^{z} = 4TIGP$

Now let's find under which conditions these three equations result in gravitational collapse. These will be some brotal pages of calculations, but bear with me because the result is worth it and we will do some interesting math in the process too

First, let us assume that the disk is infinite-simply thin and integrate the equations in z, with $\mathcal{E} = \int dz$: <u>∂</u>E + (V·∇)E = - E ∇· U $\frac{\partial u}{\partial t} + (v \cdot \nabla)v = -\frac{1}{\varepsilon}\nabla P - \nabla \vec{\ell}$

where $P = \epsilon_s^2$. For the Poisson equation, we substitute $p = \epsilon_s(2)$ $\nabla_s^2 f = 4TTG\epsilon_s(2)$

Now let's expand the momentum equations in cylindrical acordinates: $\frac{3 \sqrt{R}}{2t} + \sqrt{R} \frac{3 \sqrt{R}}{2R} + \frac{\sqrt{4}}{R} \frac{3 \sqrt{R}}{2\phi} - \frac{\sqrt{4}}{R} = -\frac{3}{2R} \frac{2}{E} - \frac{1}{2\phi} \frac{3\phi}{2R}$ $\frac{3 \sqrt{4}}{2R} + \sqrt{2} \frac{3 \sqrt{4}}{R} + \frac{\sqrt{4}}{2\phi} \frac{3 \sqrt{4}}{R} + \frac{\sqrt{4}}{2\phi} \frac{5 \sqrt{4}}{R} = -\frac{1}{2} \frac{32}{E} - \frac{1}{2\phi} \frac{3\phi}{R}$ $\frac{3 \sqrt{4}}{2R} + \sqrt{2} \frac{3 \sqrt{4}}{R} + \frac{\sqrt{4}}{2\phi} \frac{3 \sqrt{4}}{R} + \frac{\sqrt{4}}{2\phi} \frac{5 \sqrt{4}}{R} = -\frac{1}{2} \frac{32}{E} - \frac{1}{2\phi} \frac{3\phi}{R}$

Now let's define Lase state and perturbation. We decompose UP = RR + NA;

where \mathcal{R} is the Keplerian motion (base state) and $\mathcal{M} \ll \mathcal{R} \approx \text{perturbation}$. For the radial direction, $\mathcal{V}_r = \mathcal{M}_r$, so: $\frac{\partial u_{R}}{\partial t} + u_{R} \frac{\partial u_{R}}{\partial r} + \frac{\lambda}{\partial \phi} \frac{\partial u_{R}}{\partial \phi} - \frac{\lambda^{2}R}{2\pi} - 2\lambda u_{\varphi} = -\frac{\partial \Phi}{\partial r} - \frac{1}{2} \frac{\partial P}{\partial r}$ $\frac{\partial u_{\phi} + u_{\kappa}}{\partial R} \frac{\partial (\mathcal{J}_{\Gamma} + U_{\phi})}{\partial R} + \left(\frac{\mathcal{R} + U_{\phi}}{\mathcal{R}} \right) \frac{\partial u_{\phi}}{\partial \phi} + \mathcal{R} u_{r} + \frac{u_{\phi} u_{r}}{\mathcal{R}} = -\frac{1}{2} \frac{\partial \overline{\varphi}}{\partial \overline{\varphi}} - \frac{1}{2} \frac{\partial \overline{P}}{\partial \overline{\varphi}}$ (1)(エ) The second term in eq 2 contains the shear term $\frac{\partial (\mathcal{R}R)}{\partial R} = \mathcal{R} + \frac{R}{\partial \mathcal{R}} = \mathcal{R} \left(\frac{1 + \partial \ln \mathcal{R}}{\partial \ln R} \right) = \mathcal{R} \left(\frac{1 - 4}{\partial \ln R} \right)$

where $q = -\partial h \Lambda$, from $R \propto R^{-\frac{3}{2}}$ is the shear parameter.

We can then rewrite ESII as:

 $\frac{\partial u_{\varphi}}{\partial t} + \begin{pmatrix} h - q \end{pmatrix} \mathcal{L} u_{r} + \frac{\partial u_{\varphi}}{\partial r} + \begin{pmatrix} \mathcal{L} R + u_{\varphi} \end{pmatrix} \frac{\partial u_{\varphi}}{\partial \varphi} + \frac{u_{\varphi} u_{r}}{R} = -\frac{1}{2} \frac{\partial \overline{P}}{\partial \varphi} - \frac{1}{R} \frac{\partial \overline{P}}{\partial \varphi}$ $\frac{\partial U_{\varphi}}{\partial r} + \begin{pmatrix} \mathcal{L} R + u_{\varphi} \end{pmatrix} \frac{\partial u_{\varphi}}{\partial \varphi} + \frac{u_{\varphi} u_{r}}{R} = -\frac{1}{2} \frac{\partial \overline{P}}{\partial \varphi} - \frac{1}{R} \frac{\partial \overline{P}}{\partial \varphi}$ $\frac{\partial U_{\varphi}}{\partial r} + \begin{pmatrix} \mathcal{L} R + u_{\varphi} \end{pmatrix} \frac{\partial u_{\varphi}}{\partial \varphi} + \frac{u_{\varphi} u_{r}}{R} = -\frac{1}{2} \frac{\partial \overline{P}}{\partial \varphi} - \frac{1}{R} \frac{\partial \overline{P}}{\partial \varphi}$ $\frac{\partial U_{\varphi}}{\partial r} + \frac{u_{\varphi} u_{r}}{R} = -\frac{1}{2} \frac{\partial \overline{P}}{\partial \varphi} - \frac{1}{R} \frac{\partial \overline{P}}{\partial \varphi}$ $\frac{\partial U_{\varphi}}{\partial r} + \frac{u_{\varphi} u_{r}}{R} = -\frac{1}{2} \frac{\partial \overline{P}}{\partial \varphi} - \frac{1}{R} \frac{\partial \overline{P}}{\partial \varphi}$



$R = R_0 + \alpha$	•	Ronza
$\phi = \frac{y}{R_{0}}$) ;	Rossy

where Ro is a general location in the disk. This approximation means that we are looking at a small box inside the disk where arreative terms can be Ignored. Under this approximation, the equations become

 $\frac{\partial U_{x} + U_{x} \partial U_{x} + U_{y} \partial U_{x} - \lambda^{2} u - \lambda \lambda - \lambda \lambda U_{y} = -\frac{\partial 2}{\partial x} - \frac{\partial 2}{\partial x} - \frac{\partial 2}{\partial x} = -\frac{\partial 2}{\partial$ $\partial v_{y} + (2-q) \mathcal{R} u_{x} + \mathcal{V}_{x} \frac{\partial}{\partial y} v_{y} + \frac{\partial}{\partial y} \frac{\partial}{\partial y} = -\frac{\partial}{\partial z} - \frac{\partial}{\partial z} \frac{\partial}{\partial y}$ where $v_{k} = \Re R$ is the Keplerian motion. It represents a translation of the whole box and can be removed. $V \rightarrow V - V_{k}$.

So, we are left with: $\frac{\partial \xi}{\partial t} + \nabla \cdot (\xi v) = 0$ $\frac{\partial \sigma}{\partial t} + \left(v \cdot \sigma \right) v = - \nabla p - \nabla \phi - 2\Lambda x v + \mathcal{L} \Gamma + q \mathcal{L} v_{r} \dot{g}$ $\nabla^2 \underline{a} = (\Pi (\mathcal{E}) (\mathcal{A}))$

Now let us decompose the other quantities into base state and perturbation.

 $\mathcal{E} = \mathcal{E}_{a} + \mathcal{E}_{1} \left(\mathcal{R}_{a} \mathcal{R}_{a}^{\dagger} \right)$ $\mathcal{I} = \mathcal{I}_{1} \left(\mathcal{R}_{a} \mathcal{R}_{a}^{\dagger} \right)$ $p = p_0 + p_1(a, y, t)$ $\overline{\mathcal{B}} = \overline{\mathcal{B}}_0 + \overline{\mathcal{A}}_1(a, y, t)$

Assuming again that 4, 224 The unperturbed state, $\mathcal{E} = \mathcal{E}_0$, $\overline{\mathcal{P}} = \overline{\mathcal{E}}_0$, v = 0; $p = P_0$, yields simply $\nabla \underline{a}_{c} = \mathcal{N}^{2} \vec{r} = \mathcal{N}^{2} (\pi \hat{n} + 5\beta)$

which is the condition of centrifical balance.

The equation for the perturbations Lecome $\frac{\partial \mathcal{E}_{1}}{\partial t} + \mathcal{E}_{2} \nabla \mathcal{V} = 0$ $\frac{\partial \mathcal{V}}{\partial t} = -\frac{c_{1}^{2}}{\mathcal{E}_{1}} \nabla \mathcal{E}_{1} - \nabla \dot{\phi}_{1} - 2\mathcal{R}_{x}\mathcal{V} + q\mathcal{L} \mathcal{V}_{x} \hat{\mathcal{Y}}$ でき、= 4762,6(2)

We still have time and space derivatives that we can't yet solve. To advance, let us guess what these variations should be we can decompose the variations in Fourier modes: $\psi_1 = \psi_2 e^{i(kx - \omega t)}$

whose variation in time and space is known. The equations become

 $\mathcal{E}_{1} [X_{1}\gamma_{1}t] = \mathcal{E}_{\alpha} e^{i} (K_{\lambda} - \omega t)$ $\mathcal{I}_{1} = (\mathcal{I}_{\alpha} \times \widehat{\pi} + \mathcal{I}_{\gamma} \widehat{\gamma}) e^{i} (K_{\lambda} - \omega t)$ In = In e (Kn-it) (2 plane only) The last equation is only valid for z=0, because of the Dirac delta.

→ ₹≠0 ₹1 = 20 e (Kx-at) f(2) And we require $\nabla^2 \overline{\Phi}_1 = 0$ for $z \neq 0$ This equation gives $q_{5}t = \kappa_{5}t$ dz^2 : f= Ae^{-K+} + Be^{K+} In must be finite at 2-) IO, so B=0 g_= = = e (Kx-w) - 1e+1 Next we need to find Ea, Uxa, Uya and Da. For that, we use the poisson equation $\nabla^{2} = 4\pi 6 \epsilon_{1} \delta(\epsilon_{2})$ Like the RHS, the LHS must be zero everywhere except at z=0. Let us integrate between - E and E, and then take the limit E=0

 $\int_{-\epsilon}^{\epsilon} \nabla^2 \varphi_1 dA = \int_{-\epsilon}^{\epsilon} 4\Pi G \mathcal{E}_1 S(A) dA$

7ekk himit E->0 -2112 = 4TTGE ₫1 = - 271 GZa e i(Kx-w+) - 1k1z The equation above allows us to substitute \$\$ in the momentum equation. The resulting equations are $-i\omega \mathcal{E}_{a} = -i\mathcal{K}\mathcal{E}_{o} \sqrt{a_{x}}$ $-i\omega \sqrt{a_{x}} = -G^{2}i\mathcal{K}\mathcal{E}_{a} + 2\Pi Gi\mathcal{E}_{a}\mathcal{K} + 2\mathcal{R}\sqrt{a_{y}}$ $= -i\omega \sqrt{a_{y}} = -(2-q)\mathcal{R}\sqrt{a_{x}}$ This is a linear system of 3 variables and 3 equations:

 $-i\omega \begin{bmatrix} \xi_{\alpha} \\ J_{\alpha}x \\ U_{\alpha}y \end{bmatrix} = \begin{bmatrix} 0 & -ik\xi & 0 \\ -\xi^{2}ik + 2\pi Gik & 0 & 2\lambda & U_{\alpha}y \\ \overline{\xi}_{3} & |k| & 0 & 2\lambda & U_{\alpha}y \\ 0 & -(2-g) & 0 & U_{\alpha}y \end{bmatrix}$

which yields the following equation for the oscilk-tion frequency w. $\omega^{2} = \zeta_{3}^{2} k^{2} - 2\pi G \mathcal{E}_{0} |k| + 2(2-q) R^{2}$ The first term is due to pressure. The second term is due to self-gravity. The third term is due to rotation, (Notice that in the absence of pressure and self-gravity, the solution is $\omega^2 = \chi^2$

with $K^2 = 2(z-q)R^2$ being a natural frequency of the system. If a particle or gas parcel is disturbed from its orbit, it will osallate around its equilibrium orbital position at this frequency. It this thus called epicyclic frequency.

The system will be: stable if w2 >>> (w real -> >> cillation) Unstable if w2 <>> (w imag -> part grows reponentially) Rotational term K stabilizing in all scales Ressure term G'k' strong stebilization at high k Self-gravity -2TIGE, 14 DESTABILIZING $k_{crit} = T_{6} \mathcal{E}_{6} \quad \rho r \quad \omega^{2} < 0$ $C_{\rm S}^2$ $w^2(k_{mt})=0$, yields csR_TT $\frac{GE_{S}}{Q = 45R}$ $\frac{Q = 45R}{T GE}$ for instability, Q<1

For typical disk parameters for c5 ~ 0.5 cm/s, Q=1 meens ε ≈ 1.5×10 3/cm² The critical wavelength Lent = 2cs² 62 will yield a collapsing mass: $M_{p} \sim \pi \lambda^{2} \varepsilon \sim \frac{4\pi G}{G^{2} \varepsilon} \sim 5M_{30P}$

This shows that this mechanism, if operative, should produce gas giant planets.

Show HR 87-99 as possible case of GI planets