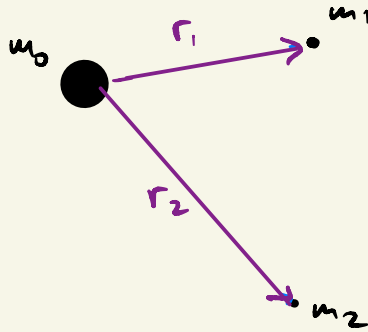


3-BODY PROBLEM



$$u_i = -\frac{G(m_0 + m_i)}{r_i} - \sum_{\substack{j=1 \\ j \neq i}}^N Gm_j \left[\frac{1}{|\vec{r}_j - \vec{r}_i|} - \frac{\vec{r}_i \cdot \vec{r}_j}{r_j^3} \right]$$

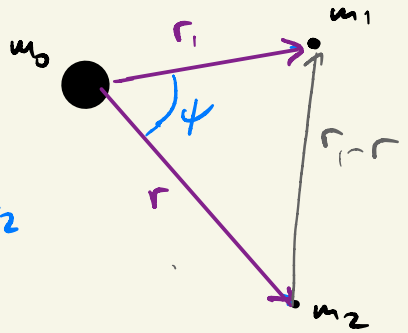
$$m_2 = 0$$

$$u_1 = -\frac{G(m_0 + m_1)}{r_1} \quad \text{2-BODY MOTION}$$

$$u_2 = -\frac{Gm_0}{r_2} - Gm_1 \left[\frac{1}{|\vec{r}_1 - \vec{r}_2|} - \frac{\vec{r}_2 \cdot \vec{r}_1}{r_1^3} \right]$$

$$H = -\frac{Gm_0}{2a} - Gm_1 \left[\frac{1}{|\vec{r}_1 - \vec{r}_2|} - \frac{\vec{r}_2 \cdot \vec{r}_1}{r_1^3} \right]$$

$$H_{\text{PERT}} = -Gm_1 \left[\frac{1}{|r_1 - r|} - \frac{\vec{r} \cdot \vec{r}_1}{r_1^3} \right]$$



$$|r_1 - r| = (r_1^2 + r^2 - 2rr_1 \cos \phi)^{1/2}$$

$$\frac{1}{|r_1 - r|} = \frac{1}{(r_1^2 + r^2 - 2rr_1 \cos \phi)^{1/2}}$$

$$\sum_{n=0}^{\infty} P_n(x) t^n = \frac{1}{\sqrt{1 - 2xt + t^2}}$$

LEGENDRE
POLYNOMIALS

$$\frac{1}{|r_1 - r|} = \frac{1}{r_1} \frac{1}{\sqrt{1 - 2(r/r_1) \cos \phi + (r/r_1)^2}}$$

$$t = \frac{r}{r_1}$$

$$x = \cos \phi$$

$$\frac{1}{|r_1 - r|} = \frac{1}{r_1} \sum_{n=0}^{\infty} \left(\frac{r}{r_1} \right)^n P_n(\cos \phi)$$

$$H_{\text{PERT}} = -Gm_1 \left[\frac{1}{r_1} \sum_{n=0}^{\infty} \left(\frac{r}{r_1} \right)^n P_n(\cos\psi) - \frac{\vec{r} \cdot \vec{r}_1}{r_1^3} \right]$$

$$\vec{r} \cdot \vec{r}_1 = r_1 r \cos\psi$$

$$P_0(x) = 1$$

$$= r_1 r P_1(\cos\psi)$$

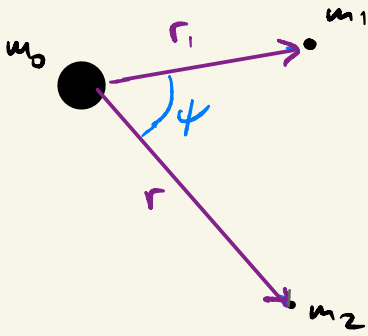
$$P_1(x) = x$$

$$\frac{\vec{r} \cdot \vec{r}_1}{r_1^3} = \frac{r}{r_1^2} P_1(\cos\psi)$$

$$H_{\text{PERT}} = -Gm_1 \left\{ \frac{1}{r_1} \left[P_0(\cos\psi) + \frac{r}{r_1} P_1(\cos\psi) + \sum_{n=2}^{\infty} \left(\frac{r}{r_1} \right)^n P_n(\cos\psi) \right] - \frac{r}{r_1^2} P_1(\cos\psi) \right\}$$

$$= -\frac{Gm_1}{r_1} \left[1 + \sum_{n=2}^{\infty} \left(\frac{r}{r_1} \right)^n P_n(\cos\psi) \right]$$

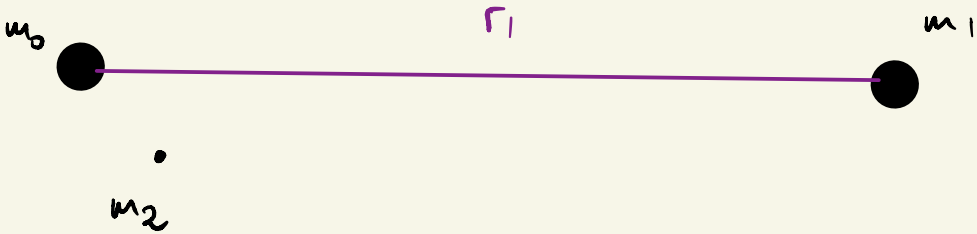
$$H_{\text{PERT}} = -\frac{Gm_1}{r_1} \sum_{n=2}^{\infty} \left(\frac{r}{r_1} \right)^n P_n(\cos\psi)$$



$$H_{\text{PERT}} = -\frac{Gm_1}{r_1} \sum_{n=2}^{\infty} \left(\frac{r}{r_1}\right)^n P_n(\cos\phi)$$

$$\approx -\frac{Gm_1}{r_1} \left(\frac{r}{r_1}\right)^2 P_2(\cos\phi)$$

$$r \ll r_1$$



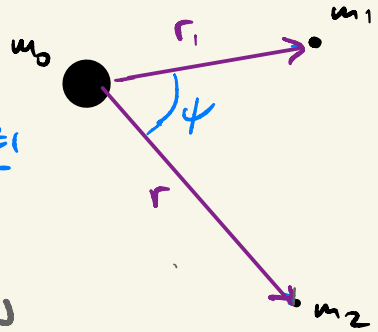
$$H_{\text{PERT}} = - \frac{Gm_1}{r_1} \sum_{n=2}^{\infty} \left(\frac{r}{r_1} \right)^n P_n(\cos \psi)$$

KEEP ONLY THE $n=2$ TERM ; $P_2(x) = \frac{1}{2}(3x^2 - 1)$

$$H_{\text{PERT}} \approx - \frac{Gm_1}{r_1} \left(\frac{r}{r_1} \right)^2 P_2(\cos \psi)$$

$$H_{\text{PERT}} \approx - \frac{Gm_1}{2} \frac{r^2}{r_1^3} [3 \cos^2 \psi - 1]$$

$$\cos \psi = \frac{\vec{r} \cdot \vec{r}_1}{r r_1} = \frac{x x_1 + y y_1 + z z_1}{r r_1}$$



IF THE ORBITS ARE KEPLERIAN

$$\frac{x}{r} = \cos \Omega \cos(\omega + f) - \sin \Omega \sin(\omega + f) \cos I$$

$$\frac{y}{r} = \sin \Omega \cos(\omega + f) + \cos \Omega \sin(\omega + f) \cos I$$

$$\frac{z}{r} = \sin(\omega + f) \sin I$$

$$\cos \psi = \frac{\vec{r} \cdot \vec{r}_1}{r r_1} = \frac{x x_1 + y y_1 + z z_1}{r r_1}$$

$$\frac{x}{r} = \cos \Omega \cos(\omega + f) - \sin \Omega \sin(\omega + f) \cos I$$

$$\frac{y}{r} = \sin \Omega \cos(\omega + f) + \cos \Omega \sin(\omega + f) \cos I$$

$$\frac{z}{r} = \sin(\omega + f) \sin I$$

$$\cos \psi = \frac{x x_1}{r r_1} + \frac{y y_1}{r r_1} + \frac{z z_1}{r r_1} = \quad \Omega_1 = \omega_1 = 0$$

$$f_1 = M_1$$

$$= [\cos \Omega \cos(\omega + f) - \sin \Omega \sin(\omega + f) \cos I] \times$$

$$[\cos \Omega_1 \cos(\omega_1 + f_1) - \sin \Omega_1 \sin(\omega_1 + f_1) \cos I_1]$$

$$+ [\sin \Omega \cos(\omega + f) + \cos \Omega \sin(\omega + f) \cos I] \times$$

$$[\sin \Omega_1 \cos(\omega_1 + f_1) + \cos \Omega_1 \sin(\omega_1 + f_1) \cos I_1]$$

$$+ [\sin(\omega + f) \sin I] [\sin(\omega_1 + f_1) \sin I_1]$$

$$\cos \psi \quad (I_1 = \Omega_1 = \omega_1 = 0)$$

$$= [\cos \Omega \cos(\omega + f) - \sin \Omega \sin(\omega + f) \cos I] \cos \mu_1$$

$$+ [\sin \Omega \cos(\omega + f) + \cos \Omega \sin(\omega + f) \cos I] \sin \mu_1$$

$$H_{\text{PERT}} \approx -\frac{G m_1}{2} \frac{r^2}{r_1^3} [3 \cos^2 \psi - 1]$$

θ	J
M	E
ω	L
Ω	L_2

$$\frac{\partial H}{\partial \theta} = -j \neq 0$$