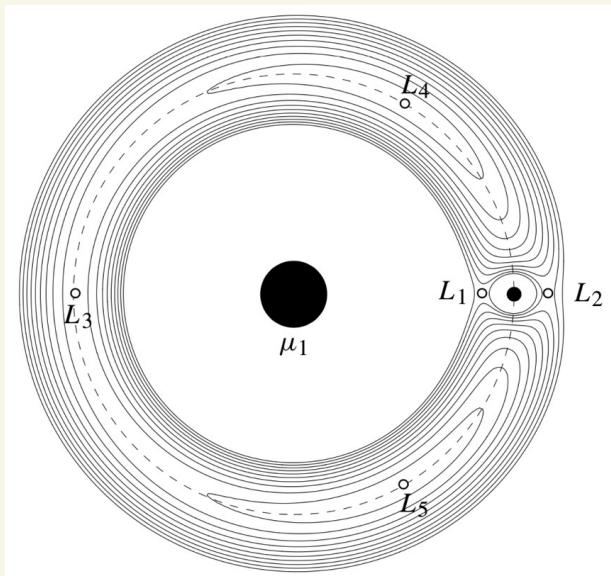


STABILITY OF LAGRANGIAN POINTS



$$\ddot{x} - 2n\dot{y} = \frac{\partial U}{\partial x}$$

$$\ddot{y} + 2n\dot{x} = \frac{\partial U}{\partial y}$$

$$n=1$$

$$\ddot{x} - 2y = \frac{\partial U}{\partial x}$$

$$\ddot{y} + 2x = \frac{\partial U}{\partial y}$$

EQUILIBRIUM POINT (x_0, y_0)

$$x = x_0 + x \quad y = y_0 + y$$

x, y : small displacement

$$\ddot{x} - 2\dot{y} = \frac{\partial U}{\partial x} \approx \cancel{\frac{\partial U}{\partial x}}|_0 + x \frac{\partial}{\partial x} \left(\frac{\partial U}{\partial x} \right)|_0 + y \frac{\partial}{\partial y} \left(\frac{\partial U}{\partial x} \right)|_0$$

$$\ddot{y} + 2\dot{x} = \frac{\partial U}{\partial y} \approx \cancel{\frac{\partial U}{\partial y}}|_0 + y \frac{\partial}{\partial y} \left(\frac{\partial U}{\partial y} \right)|_0 + x \frac{\partial}{\partial x} \left(\frac{\partial U}{\partial y} \right)|_0$$

$$\frac{\partial U}{\partial x}|_0 = 0 \quad \frac{\partial U}{\partial y}|_0 = 0$$

$$\ddot{x} - 2\dot{y} = x \frac{\partial^2 u}{\partial x^2} \Big|_0 + y \frac{\partial^2 u}{\partial y \partial x} \Big|_0 + O(x^2, y^2, xy)$$

$$\ddot{y} + 2\dot{x} = y \frac{\partial^2 u}{\partial y^2} \Big|_0 + x \frac{\partial^2 u}{\partial x \partial y} \Big|_0 + O(x^2, y^2, xy)$$

$$U_{xx} = \frac{\partial^2 u}{\partial x^2} \Big|_0 \quad U_{yy} = \frac{\partial^2 u}{\partial y^2} \Big|_0 \quad U_{xy} = \frac{\partial^2 u}{\partial x \partial y} \Big|_0$$

$$\ddot{x} - 2\dot{y} = x U_{xx} + y U_{xy}$$

$$\ddot{y} + 2\dot{x} = x U_{xy} + y U_{yy}$$

$$\begin{bmatrix} \dot{x} \\ \dot{y} \\ \vdots \\ \ddot{x} \\ \ddot{y} \end{bmatrix} = \begin{bmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ U_{xx} & U_{xy} & 0 & 2 \\ U_{xy} & U_{yy} & -2 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \\ \vdots \\ \dot{x} \\ \dot{y} \end{bmatrix}$$

$$A = \begin{bmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ U_{xx} & U_{xy} & 0 & 2 \\ U_{xy} & U_{yy} & -2 & 0 \end{bmatrix} \quad |A - \lambda I| = 0$$

$$|A - \lambda I| = 0$$

$$\lambda^4 + (4 - U_{xx} - U_{yy})\lambda^2 + U_{xx}U_{yy} - U_{xy}^2 = 0$$

$$\begin{aligned}\lambda_{1,2} &= \pm \left\{ \frac{1}{2} \left(U_{xx} + U_{yy} - 4 \right) \right. \\ &\quad \left. - \frac{1}{2} \left[(4 - U_{xx} - U_{yy})^2 - 4(U_{xx}U_{yy} - U_{xy}^2) \right]^{1/2} \right\}^{1/2}\end{aligned}$$

$$\begin{aligned}\lambda_{3,4} &= \pm \left\{ \frac{1}{2} \left(U_{xx} + U_{yy} - 4 \right) \right. \\ &\quad \left. + \frac{1}{2} \left[(4 - U_{xx} - U_{yy})^2 - 4(U_{xx}U_{yy} - U_{xy}^2) \right]^{1/2} \right\}^{1/2}\end{aligned}$$

$$\lambda_{1,2} = \pm (j_1 + i k_1) \quad \lambda_{3,4} = \pm (j_2 + i k_2)$$

$$X = \sum_{j=1}^4 \alpha_j e^{\lambda_j t} \quad Y = \sum_{j=1}^4 \beta_j e^{\lambda_j t}$$

IF $j \neq 0$ GROWTH UNSTABLE

IF $j = 0$ OSCILLATION STABLE

COLLINEAR POINTS

$$U = \frac{1}{2} (x^2 + y^2) + \frac{\mu_1}{r_1} + \frac{\mu_2}{r_2}$$

$$\frac{\partial U}{\partial x} = x + \mu_1 \frac{\partial}{\partial x} \left(\frac{1}{r_1} \right) + \mu_2 \frac{\partial}{\partial x} \left(\frac{1}{r_2} \right)$$

$$\frac{\partial U}{\partial y} = y + \mu_1 \frac{\partial}{\partial y} \left(\frac{1}{r_1} \right) + \mu_2 \frac{\partial}{\partial y} \left(\frac{1}{r_2} \right)$$

$$\frac{\partial^2 U}{\partial x^2} = 1 + \mu_1 \frac{\partial^2}{\partial x^2} \left(\frac{1}{r_1} \right) + \mu_2 \frac{\partial^2}{\partial x^2} \left(\frac{1}{r_2} \right)$$

$$\frac{\partial^2 U}{\partial y^2} = 1 + \mu_1 \frac{\partial^2}{\partial y^2} \left(\frac{1}{r_1} \right) + \mu_2 \frac{\partial^2}{\partial y^2} \left(\frac{1}{r_2} \right)$$

$$\frac{\partial^2 U}{\partial x \partial y} = \mu_1 \frac{\partial^2}{\partial x \partial y} \left(\frac{1}{r_1} \right) + \mu_2 \frac{\partial^2}{\partial x \partial y} \left(\frac{1}{r_2} \right)$$

$$r_1 = (x + \mu_2)^2 + y^2 \quad \therefore \quad \frac{\partial^2 U}{\partial x \partial y} = 0$$
$$r_2 = (x - \mu_1)^2 + y^2$$

$$\frac{\partial}{\partial y} \left(\frac{1}{r_1} \right) = -\frac{1}{r_1^2} \frac{\partial r_1}{\partial y} = -\frac{1}{r_1^2} 2y \quad \therefore \frac{\partial^2}{\partial y^2} = +\frac{4y}{r_1^3} - \frac{2}{r_1^2}$$

$$X = \sum_{j=1}^4 \alpha_j e^{\lambda_j t} \quad Y = \sum_{j=1}^4 \beta_j e^{\lambda_j \cdot t}$$

$$r_1 = (x - \mu_2)^2 + \gamma^2$$

$$r_2 = (x - \mu_1)^2 + \gamma^2$$

$$U = \frac{1}{2} (x^2 + \gamma^2) + \frac{\mu_1}{r_1} + \frac{\mu_2}{r_2}$$

$$\frac{\partial U}{\partial x} = x + \mu_1 \frac{\partial}{\partial x} \left(\frac{1}{r_1} \right) + \mu_2 \frac{\partial}{\partial x} \left(\frac{1}{r_2} \right)$$

$$\frac{\partial U}{\partial y} = \gamma + \mu_1 \frac{\partial}{\partial y} \left(\frac{1}{r_1} \right) + \mu_2 \frac{\partial}{\partial y} \left(\frac{1}{r_2} \right)$$

STABILITY OF LAGRANGIAN POINTS

$$X = \sum_{j=1}^4 \alpha_j e^{\lambda_j t} \quad Y = \sum_{j=1}^4 \beta_j e^{\lambda_j t}$$

$$\lambda^4 + (4 - U_{xx} - U_{yy})\lambda^2 + U_{xx}U_{yy} - U_{xy}^2 = 0$$

$$U_{xx} = \left. \frac{\partial^2 U}{\partial x^2} \right|_0 \quad U_{yy} = \left. \frac{\partial^2 U}{\partial y^2} \right|_0 \quad U_{xy} = \left. \frac{\partial^2 U}{\partial x \partial y} \right|_0$$

$$\lambda_{1,2} = \pm \left\{ \frac{1}{2} (U_{xx} + U_{yy} - 4) - \frac{1}{2} \left[(4 - U_{xx} - U_{yy})^2 - 4(U_{xx}U_{yy} - U_{xy}^2) \right]^{1/2} \right\}^{1/2}$$

$$\lambda_{3,4} = \pm \left\{ \frac{1}{2} (U_{xx} + U_{yy} - 4) + \frac{1}{2} \left[(4 - U_{xx} - U_{yy})^2 - 4(U_{xx}U_{yy} - U_{xy}^2) \right]^{1/2} \right\}^{1/2}$$

$$\lambda_{1,2} = \pm (j_1 + i k_1) \quad \lambda_{3,4} = \pm (j_2 + i k_2)$$

U_{xx}

$$U = \frac{1}{2} (x^2 + y^2) + \frac{\mu_1}{r_1} + \frac{\mu_2}{r_2}$$

$$r_1^2 = (x + \mu_2)^2 + y^2$$

$$r_2^2 = (x - \mu_1)^2 + y^2$$

$$U = \frac{1}{2} (x^2 + y^2) + \frac{\mu_1}{r_1} + \frac{\mu_2}{r_2}$$

$$\frac{\partial U}{\partial x} = x + \mu_1 \frac{\partial}{\partial x} \left(\frac{1}{r_1} \right) + \mu_2 \frac{\partial}{\partial x} \left(\frac{1}{r_2} \right)$$

$$\frac{\partial}{\partial x} \left(\frac{1}{r_1} \right) = -\frac{1}{r_1^2} \frac{\partial r_1}{\partial x}$$

$$\frac{\partial U}{\partial x} = x - \mu_1 \frac{(x + \mu_2)}{r_1^3} - \mu_2 \frac{(x - \mu_1)}{r_2^3}$$

$$r_1^2 = (x + \mu_2)^2 + y^2$$

$$\frac{\partial r_1}{\partial x} = \frac{(x + \mu_2)}{r_1}; \quad \frac{\partial r_1}{\partial y} = \frac{y}{r_1}$$

$$\frac{\partial r_2}{\partial x} = \frac{(x - \mu_1)}{r_2}; \quad \frac{\partial r_2}{\partial y} = \frac{y}{r_2}$$

$$\boxed{\frac{\partial^2 U}{\partial x^2} = 1 + 3 \frac{\mu_1 (x + \mu_2)}{r_1^4} + 3 \frac{\mu_2 (x - \mu_1)}{r_2^4} - \frac{\mu_1}{r_1^3} - \frac{\mu_2}{r_2^3}}$$

U_{YY}

$$\boxed{\frac{\partial^2 U}{\partial y^2} = 1 + 3 \frac{\mu_1 y}{r_1^4} + 3 \frac{\mu_2 y}{r_2^4} - \frac{\mu_1}{r_1^3} - \frac{\mu_2}{r_2^3}}$$

U_{X Y}

$$\frac{\partial U}{\partial y} = y - \frac{\mu_1 y}{r_1^3} - \frac{\mu_2 y}{r_2^3}$$

$$\frac{\partial U}{\partial Y} = Y - \frac{\mu_1 Y}{r_1^3} - \frac{\mu_2 Y}{r_2^3}$$

$$\frac{\partial^2 U}{\partial X \partial Y} = 3Y \left[\frac{\mu_1(x+\mu_2)}{r_1^5} + \frac{\mu_2(x-\mu_1)}{r_2^5} \right]$$

SOLUTIONS:

$$\frac{\partial^2 U}{\partial X^2} = L + 3\frac{\mu_1(x+\mu_2)}{r_1^4} + 3\frac{\mu_2(x-\mu_1)}{r_2^4} - \frac{\mu_1}{r_1^3} - \frac{\mu_2}{r_2^3}$$

$$\frac{\partial^2 U}{\partial Y^2} = L + 3\frac{\mu_1 Y}{r_1^4} + 3\frac{\mu_2 Y}{r_2^4} - \frac{\mu_1}{r_1^3} - \frac{\mu_2}{r_2^3}$$

$$\frac{\partial^2 U}{\partial X \partial Y} = 3Y \left[\frac{\mu_1(x+\mu_2)}{r_1^5} + \frac{\mu_2(x-\mu_1)}{r_2^5} \right]$$

COLLINEAR POINTS L_1, L_2, L_3 $Y=0$

$$\frac{\partial^2 U}{\partial X^2} = L + 3\frac{\mu_1(x+\mu_2)}{r_1^4} + 3\frac{\mu_2(x-\mu_1)}{r_2^4} - \frac{\mu_1}{r_1^3} - \frac{\mu_2}{r_2^3} = L + 2\frac{\mu_1}{r_1^3} + 2\frac{\mu_2}{r_2^3}$$

$$\frac{\partial^2 U}{\partial Y^2} = L + 3\frac{\mu_1 Y}{r_1^4} + 3\frac{\mu_2 Y}{r_2^4} - \frac{\mu_1}{r_1^3} - \frac{\mu_2}{r_2^3} = L - \frac{\mu_1}{r_1^3} - \frac{\mu_2}{r_2^3}$$

$$\frac{\partial^2 U}{\partial X \partial Y} = 3Y \left[\frac{\mu_1(x+\mu_2)}{r_1^5} + \frac{\mu_2(x-\mu_1)}{r_2^5} \right] = 0$$

$$U_{xx} = L + 2A$$

$$U_{yy} = L - A$$

$$U_{xy} = 0$$

$$A = \frac{\mu_1}{(r_1)^3} + \frac{\mu_2}{(r_2)^3}$$

$$\lambda = \pm \left\{ \frac{1}{2} (U_{xx} + U_{yy} - 4) \pm \frac{1}{2} \left[(4 - U_{xx} - U_{yy})^2 - 4(U_{xx}U_{yy}) \right]^{1/2} \right\}^{1/2}$$

$$\Delta = 2$$

$$\lambda = \pm \sqrt{\frac{1}{2} (\Delta - 2)} \pm \frac{1}{2} \left[9A^2 - 8A \right]^{1/2}$$

$$L_1, L_2, L_3 \quad \lambda = \pm (j + ik) \quad j \neq 0$$

UNSTABLE

TRIANGULAR POINTS L₄, L₅

$$\frac{\partial^2 U}{\partial x^2} = L + 3 \frac{\mu_1(x+\mu_2)}{r_1^4} + 3 \frac{\mu_2(x-\mu_1)}{r_2^4} - \frac{\mu_1}{r_1^3} - \frac{\mu_2}{r_2^3} = \frac{3}{4}$$

$$r_1 = r_2 = 1$$

$$\frac{\partial^2 U}{\partial y^2} = L + 3 \frac{\mu_1 Y}{r_1^4} + 3 \frac{\mu_2 Y}{r_2^4} - \frac{\mu_1}{r_1^3} - \frac{\mu_2}{r_2^3} = \frac{9}{4}$$

$$x = \frac{1}{2} - \mu_2$$

$$\frac{\partial^2 U}{\partial x \partial y} = 3Y \left[\frac{\mu_1(x+\mu_2)}{r_1^6} + \frac{\mu_2(x-\mu_1)}{r_2^6} \right] = \pm \frac{3\sqrt{3}}{4} (1 - 2\mu_2)$$

$$y = \pm \frac{\sqrt{3}}{2}$$

$$U_{xx} = \frac{3}{4} \quad U_{yy} = \frac{9}{4} \quad U_{xy} = \pm \frac{3\sqrt{3}}{4}(1-2\mu_2)$$

$$\lambda = \pm \left\{ \frac{1}{2} (U_{xx} + U_{yy} - 4) \right. \\ \left. \pm \frac{1}{2} \left[(4 - U_{xx} - U_{yy})^2 - 4(U_{xx}U_{yy} - U_{xy}^2) \right]^{1/2} \right\}^{1/2}$$

$$U_{xx} + U_{yy} - 4 = \frac{3}{4} + \frac{9}{4} - \frac{16}{4} = -1$$

$$\lambda = \pm \left\{ -\frac{1}{2} \pm \frac{1}{2} \left[1 - 4 \left(U_{xx} U_{yy} - U_{xy}^2 \right) \right]^{1/2} \right\}^{1/2}$$

$$U_{xx}U_{yy} - U_{xy}^2 = \frac{27}{16} - \frac{27}{16} (1-2\cancel{\mu_2})^2 = 0 \quad \mu_2 \ll 1$$

$$\lambda = \pm \left(-\frac{1}{2} \pm \frac{1}{2} \right)^{1/2} = 0; \pm i \quad j=0$$

L_4, L_5

STABLE

MOTION AROUND L4 AND L5

$$\lambda = \pm \frac{1}{\sqrt{2}} \sqrt{-1 \pm \sqrt{1 - 27(1-\mu_2)\mu_2}}$$

$$1 - 27(1-\mu_2)\mu_2 > 0 \quad (\text{STABILITY})$$

$$\mu_2 \leq \frac{27 - \sqrt{621}}{54} \approx 0.04$$

FOR $\mu_2 \ll 1 \neq 0$

$$\sqrt{1 - 27(1-\mu_2)\mu_2} \approx \sqrt{1 - 27\mu_2} \approx 1 - \frac{27}{2}\mu_2$$

$$\lambda = \pm \frac{1}{\sqrt{2}} \sqrt{-1 \pm \left(1 - \frac{27}{2}\mu_2\right)} = \pm \sqrt{-\frac{1}{2} \pm \left(\frac{1}{2} - \frac{27}{4}\mu_2\right)}$$

$$\lambda_{1,2} = \pm \sqrt{-1 - \frac{27}{4}\mu_2} \approx \pm i$$

$$\lambda_{3,4} = \pm \sqrt{-\frac{27}{4}\mu_2}$$

LIBRATION

$$X = \sum_{j=1}^4 \alpha_j e^{\lambda_j t} \quad Y = \sum_{j=1}^4 \beta_j e^{\lambda_j t}$$