

THE CIRCULAR RESTRICTED THREE BODY PROBLEM

JACOBI CONSTANT

$$\ddot{\mathbf{r}} = -\frac{\mu_1}{r_1^3} \mathbf{r}_1 - \frac{\mu_2}{r_2^3} \mathbf{r}_2$$

FRAME COROTATING WITH SECONDARY

$$(\ddot{\mathbf{r}})_{\text{COROT}} = (\ddot{\mathbf{r}})_{\text{INERTIAL}} - \boldsymbol{\Omega} \times (\boldsymbol{\Omega} \times \mathbf{r}) - 2\boldsymbol{\Omega} \times \dot{\mathbf{r}}$$

$$\boldsymbol{\Omega} \equiv \Omega \hat{\mathbf{z}}$$

$$\ddot{x} - 2\Omega \dot{y} = \Omega^2 x - \mu_1 \frac{(x + \mu_2)}{r_1^3} - \mu_2 \frac{(x - \mu_1)}{r_2^3}$$

$$\ddot{y} + 2\Omega \dot{x} = \Omega^2 y - \frac{\mu_1 y}{r_1^3} - \frac{\mu_2 y}{r_2^3}$$

$$\ddot{z} = -\frac{\mu_1}{r_1^3} z - \frac{\mu_2}{r_2^3} z$$

$$\ddot{x} - 2\Omega\dot{y} = \Omega^2 x - \mu_1 \frac{(x+\mu_2)}{r_1^3} - \mu_2 \frac{(x-\mu_1)}{r_2^3}$$

$$\ddot{y} + 2\Omega\dot{x} = \Omega^2 y - \frac{\mu_1 y}{r_1^3} - \frac{\mu_2 y}{r_2^3}$$

$$\ddot{z} = -\frac{\mu_1}{r_1^3} z - \frac{\mu_2}{r_2^3} z$$

$$\ddot{x} - 2\Omega\dot{y} = \frac{\partial U}{\partial x} \quad (\dot{x})$$

$$\ddot{y} + 2\Omega\dot{x} = \frac{\partial U}{\partial y} \quad (\dot{y})$$

$$\ddot{z} = \frac{\partial U}{\partial z} \quad (\dot{z})$$

$$U = \frac{\Omega^2}{2} (x^2 + y^2) + \frac{\mu_1}{r_1} + \frac{\mu_2}{r_2}$$

$$x\ddot{x} + y\ddot{y} + z\ddot{z} = \frac{\partial U}{\partial x} \dot{x} + \frac{\partial U}{\partial y} \dot{y} + \frac{\partial U}{\partial z} \dot{z} \equiv \frac{dU}{dt}$$

JACOBI CONSTANT!

$$\dot{x}^2 + \dot{y}^2 + \dot{z}^2 + C = 2 \cdot U$$

$$C_J = 2 \cdot U - v^2$$

$$C_J = \Omega^2 (x^2 + y^2) + 2 \left(\frac{\mu_1}{r_1} + \frac{\mu_2}{r_2} \right) - v^2$$

TISSERAND PARAMETER

$$C_J = 2U - v^2$$

$$C_J = \Omega^2(x^2 + y^2) + 2\left(\frac{\mu_1}{r_1} + \frac{\mu_2}{r_2}\right) - v^2 \quad \text{COROTATIONAL}$$

$$C_J = 2\Omega(x\dot{y} - y\dot{x}) + 2\left(\frac{\mu_1}{r_1} + \frac{\mu_2}{r_2}\right) - v^2 \quad \text{INERTIAL}$$

$$\frac{v^2}{2} - \frac{1}{r} = \frac{1}{2a} \quad \rightarrow \quad v^2 = \frac{2}{r} - \frac{1}{a} \quad (\mu=1)$$

$$L = r \times \dot{r} \quad L_z = x\dot{y} - y\dot{x} \quad L_z = L \cdot \hat{z} = L \cos I$$

$$L^2 = a(1-e^2)$$

$$C_J = 2\cancel{\Omega} L \cos I + 2\left(\frac{\mu_1}{r_1} + \frac{\mu_2}{r_2}\right) - \frac{2}{r} + \frac{1}{a}$$

$\mu_1 = 1 = \Omega$
 $\mu_2 \ll \mu_1$
 $\mu_2 = 0$

$$C_J \approx 2 \cos I \sqrt{a(1-e^2)} + \frac{1}{a}$$

$$\frac{1}{2a} + \sqrt{a(1-e^2)} \cos I \approx \text{constant}$$