Violent Relaxation

Violent Telaxation

This process happens at early stages of evolution of a system. The key feature is the explicit dependence of gravitational potential $\varphi(x,t)$ on time t: $\varphi = \varphi(x,t)$

Let's try to integrate energy of a particle along its trajectory: $E = \frac{y^2}{2} + \varphi(x_i t)$

$$\frac{dE}{dt} = \frac{1}{along} = \frac{1}{2} \frac{d\vec{v}}{dt} + \frac{d\varphi}{dt}$$
but trajectory
$$\frac{d\varphi}{dt} = \frac{\partial \varphi}{\partial t} + \frac{\partial \varphi}{\partial x} \frac{dx}{dt} + \frac{\partial \varphi}{\partial y} \frac{dy}{dt} + \frac{\partial \varphi}{\partial z} \frac{dz}{dt} = \frac{\partial \varphi}{\partial t} + (\vec{v}.\vec{\nabla}) \psi$$
and
$$\frac{1}{2} \frac{d\vec{v}}{dt} = \vec{v}. d\vec{v} = -(\vec{v}.\vec{\nabla}) \vec{\varphi} \quad \text{Here we used eq. 4 motion:}$$

$$\frac{d\vec{v}}{dt} = -\nabla \varphi$$

Thus,
$$dE = \frac{\partial \varphi}{\partial t}$$

$$\Delta E \Big|_{a \text{ bong trajectory } t_o} = \int dt \cdot \frac{\partial \varphi}{\partial t} \Big|_{t \text{ rajectory } t_o}$$

We cannot take this integral, because we do not know how I changes with time. At early stages of evolution we expect that grav, potential changes significantly over short period of time. The shortest time is the dynamical time. Thus so I for startly for some expectations: $\Delta E = \int_{-\infty}^{toyn} dt \Delta U = U = E$ Toy model for violent relaxation:

Properties of violent relaxation

=> tviol. rel. = tayn

=> no dependency on particle mass: $\langle V_1^2 \rangle = \langle V_2^2 \rangle$ for $M_1 \neq M_2$

=> anisotropy is significantly reduced:

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=> a fraction of particles may escape

=> Once the system reaches a quasi-static state, φ = φ(x), violent relaxation shuts off. as such, it has a tendency to be incomplete. For example, Emitially anisotropic system will reduce anisotropy, but it will not become round.

-> redistribution of evergy between particles is typical for violent relaxation: